

# P and S Travel Time Tomography Using a Dense Array of Portable Seismographs and Earthquake Sources in Central Oklahoma

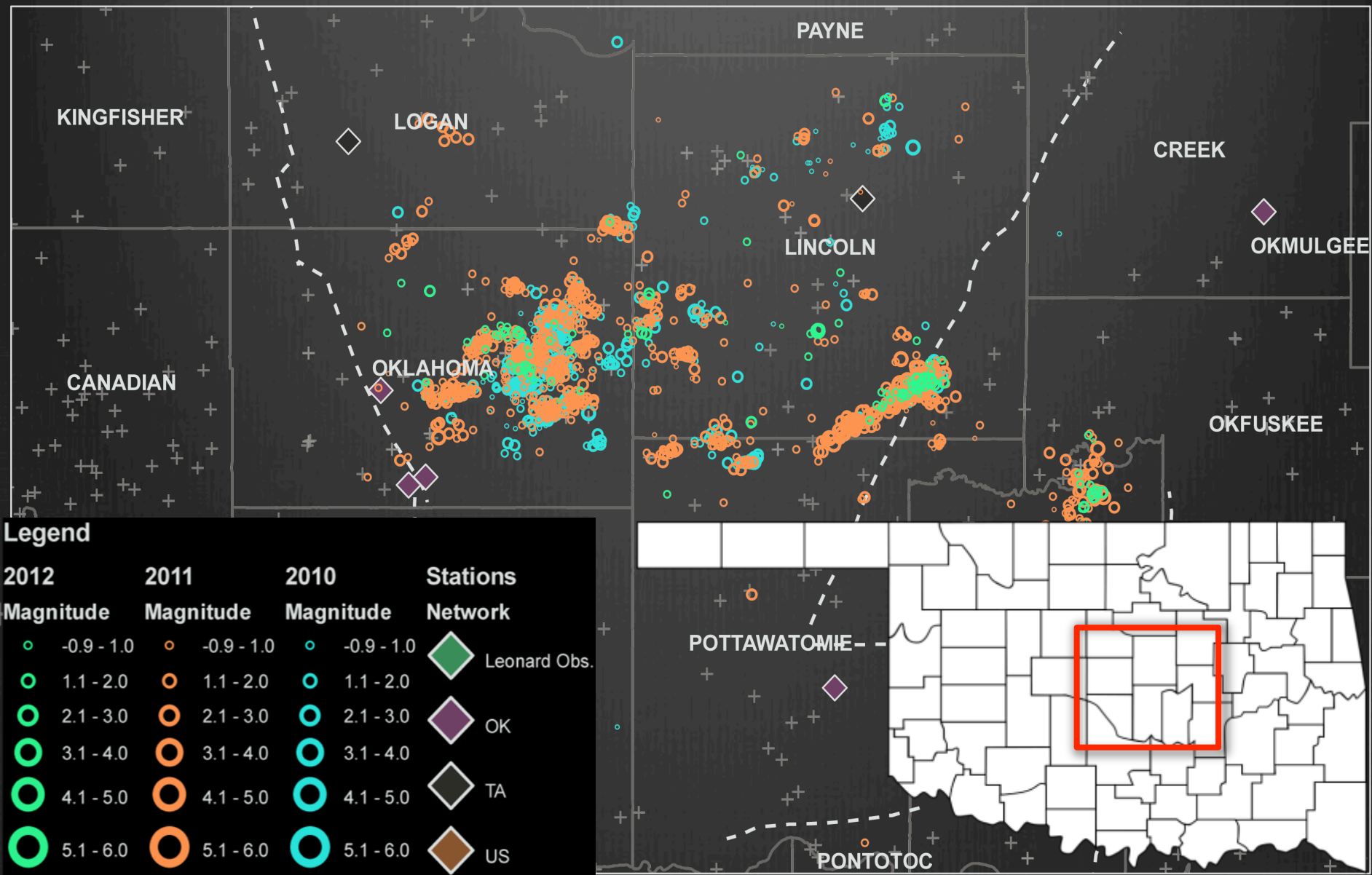
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<sup>2</sup> Oklahoma Geological Survey, Norman



# 2010-2012 Oklahoma Seismicity

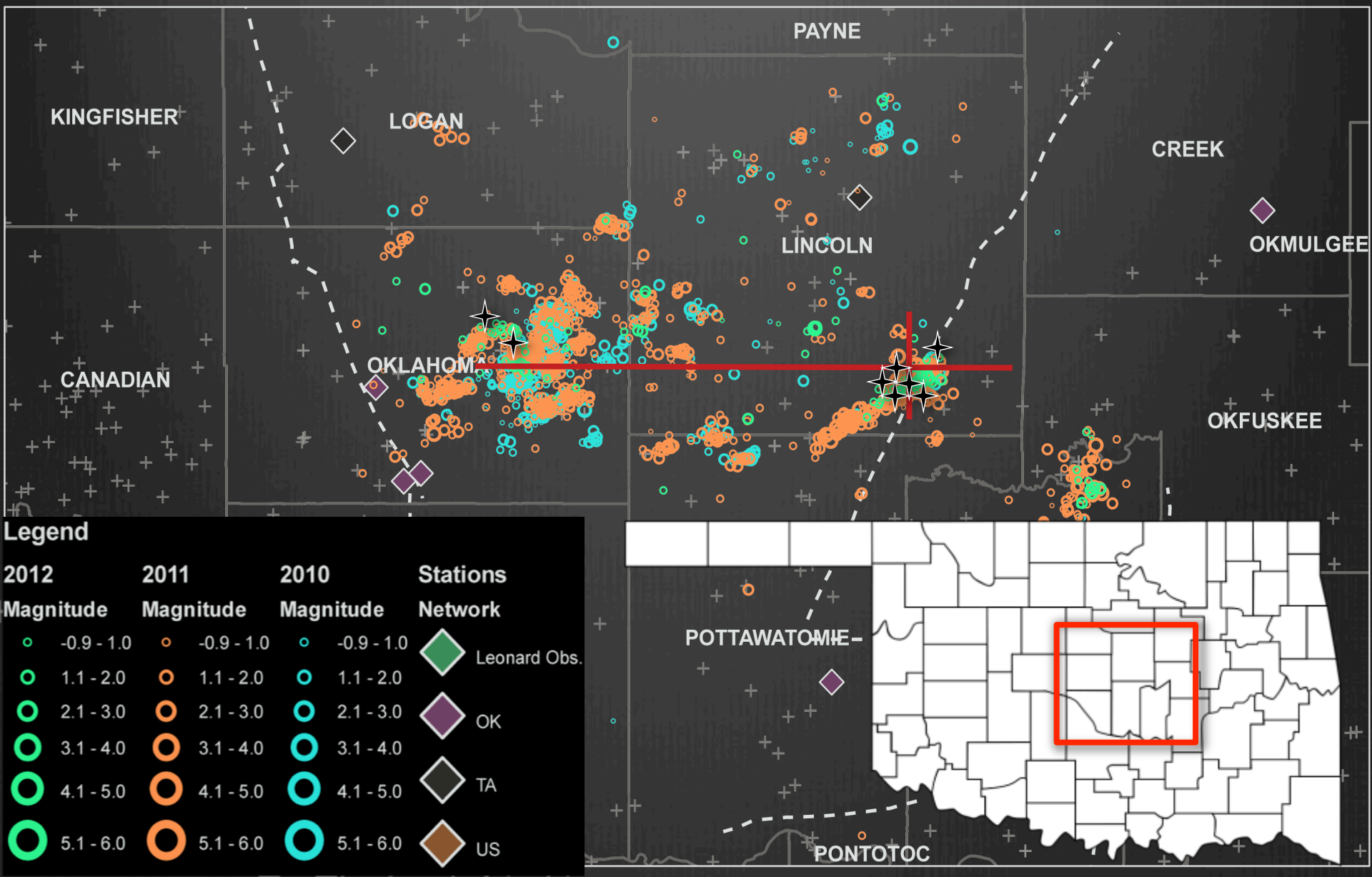


# Survey Design

Take advantage of a unique opportunity to record a reversed refraction profile using well-located earthquakes as sources

- ❶ 123 TEXAN recorders with 4.5Hz vertical geophones spanned a 68km E-W line between Jones and Prague.
  - ❶ 0.55 km average spacing
- ❶ 33 TEXAN recorders with 4.5Hz vertical geophones spanned a N-S line through Prague.
  - ❶ 0.4 km average spacing
- ❶ Recorded continually during 4 nights to minimize cultural noise.
- ❶ 2 earthquakes were recorded from the Jones swarm and 6 from the Prague sequence
  - ❶ Magnitudes 1 and 2

# Survey Design

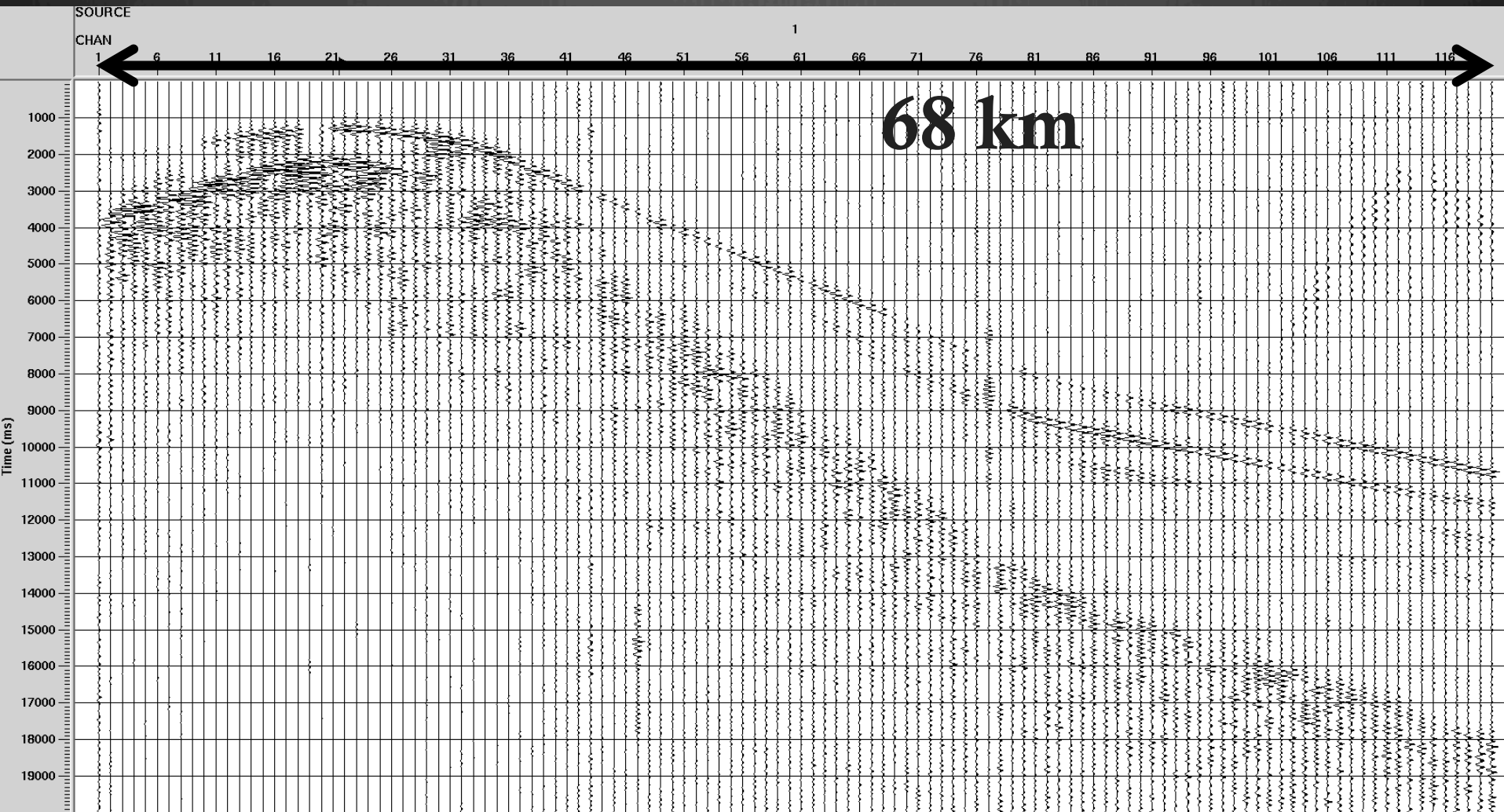




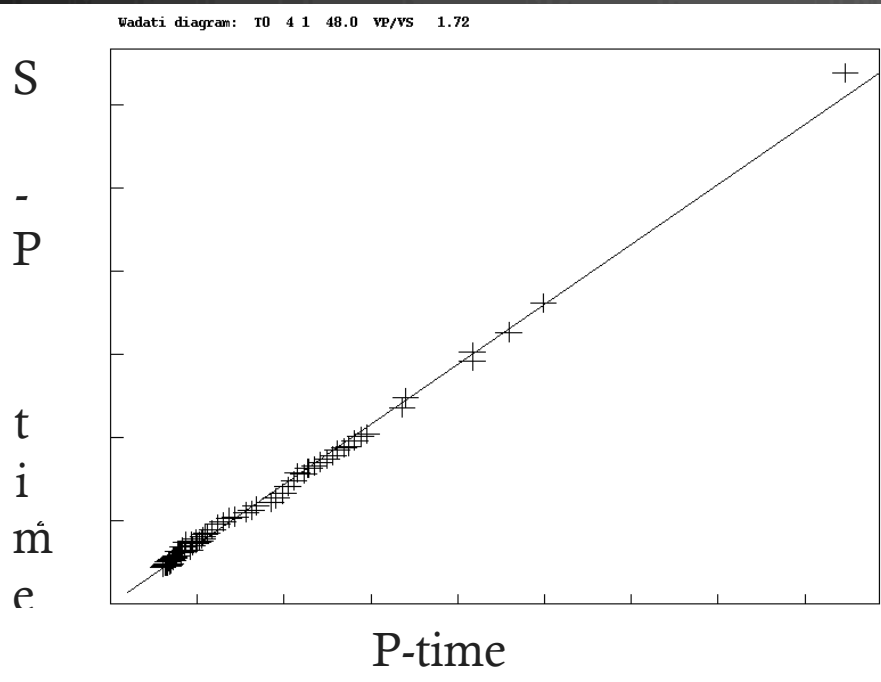
# Source Locations

- ⊗ Origin times first determined with OGS regional seismic network with Seisan
- ⊗ First breaks were picked with Landmark's ProMAX software
  - ⊗ Receiver geometry allowed for visual correlation of phases
  - ⊗ Used coherence, bandpass, AGC, trace muting, trace scaling
- ⊗ S and P travel times from ProMAX were added to the regional station phase arrival times to further refine source locations and origin times with Seisan
- ⊗ Average spacial uncertainty:
  - ⊗ 0.4km vertical
  - ⊗ 0.3km horizontal
- ⊗ Average temporal error: 0.12 seconds

# First Breaks

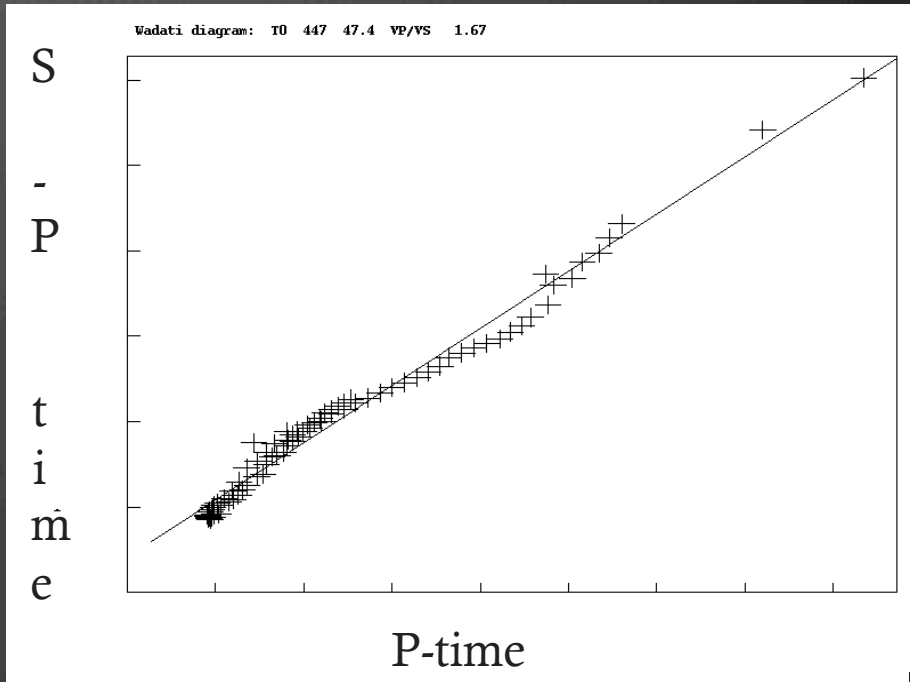


# Wadati Plots



● Jones (West) Earthquake

●  $V_p/V_s = 1.72$

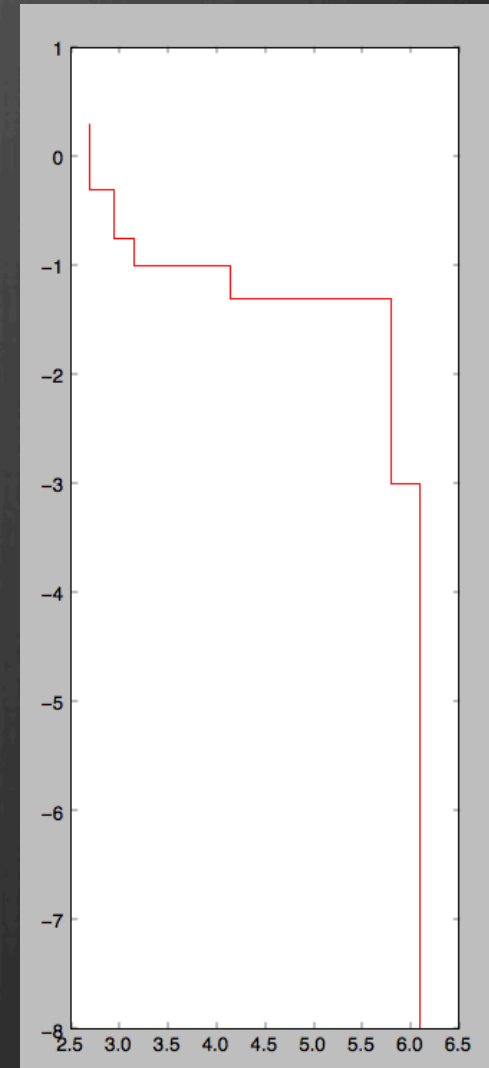


● Prague (East) Earthquake

●  $V_p/V_s = 1.67$

# Initial Model

- Depth to Basement (Luza and Lawson, 1981):
  - Jones: 2.75km
  - Prague: 1.8km
- Sonic logs show a high velocity ( $\sim 5.5\text{km/s}$ ) sedimentary package above basement at 1.5km deep in Prague
- Initial velocity model from Toth et al (2012)
  - Joint velocity and hypocenter inversion (VELEST) constrained by sonic logs and double-difference relocation (HypoDD)

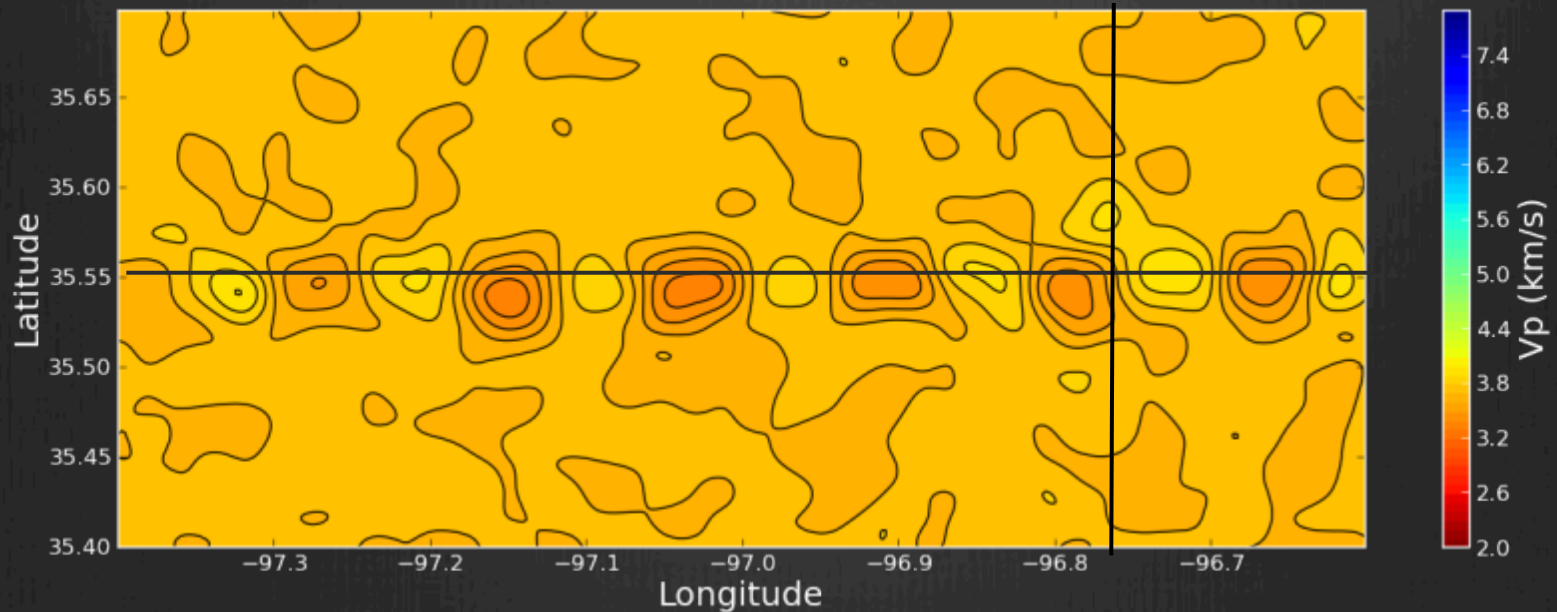
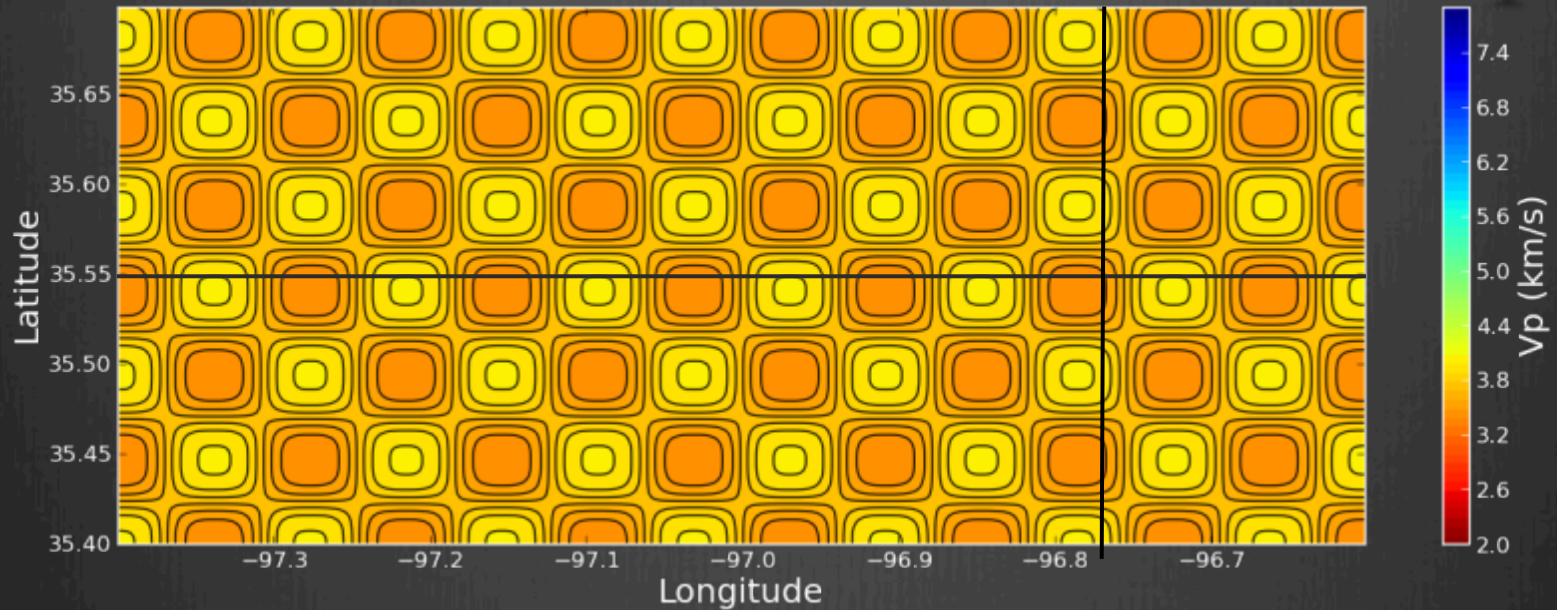


# Inversion and Checkerboard Resolution Test

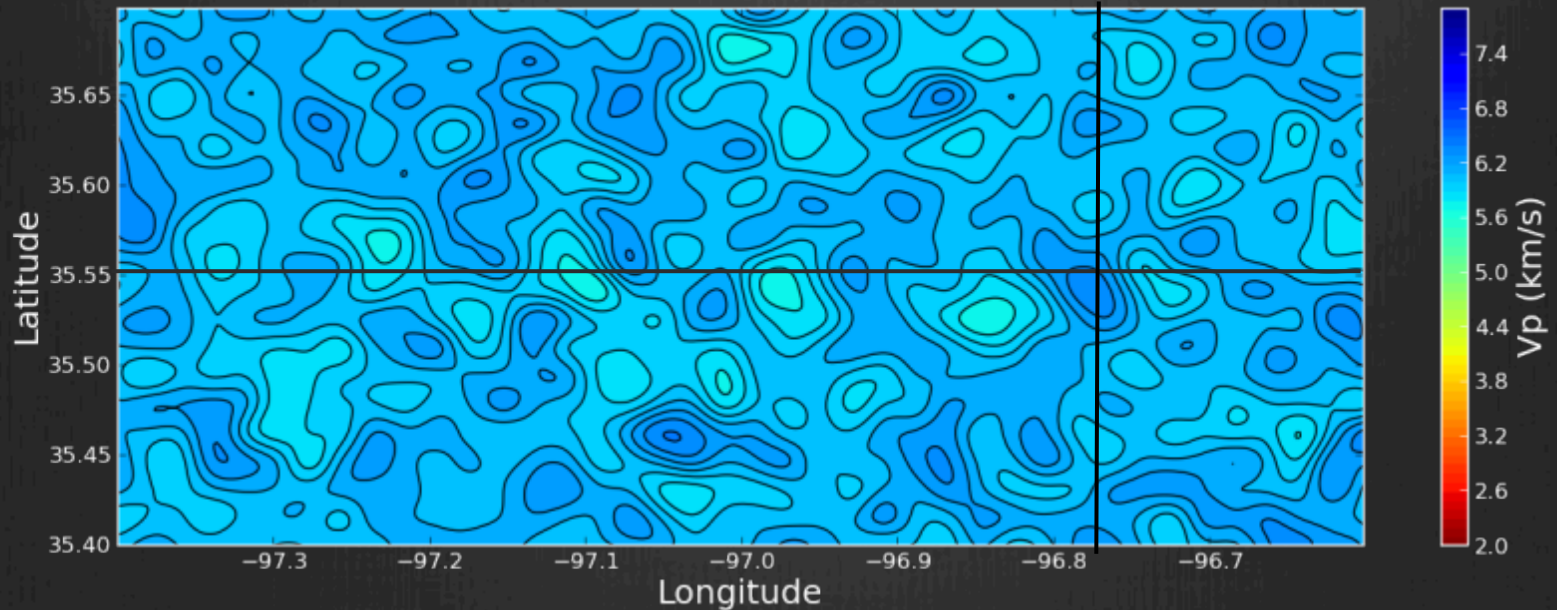
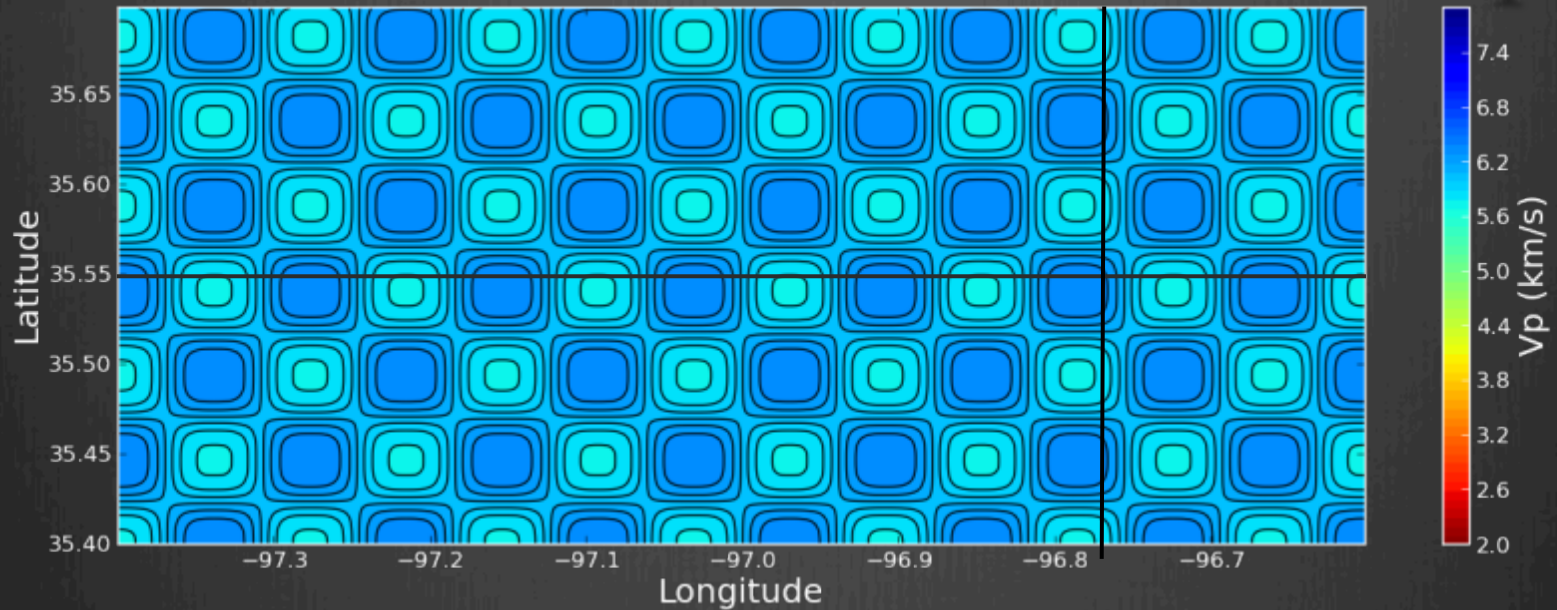
- FMtomo (Ralinson et al, 2006) was used for Checkerboard resolution tests and the forward and reverse modeling
- Checkerboard perturbations
  - 5km spacing in X,Y, and Z
  - Alternating +/- 0.3 km/s
- Checkerboard: Stopped converging after 5 iterations
  - Chi-squared misfit of 35.7 was reduced to 0.035
- Inversion: Stopped converging after 9 iterations
  - Chi-squared misfit of 5115 reduced to 11.93



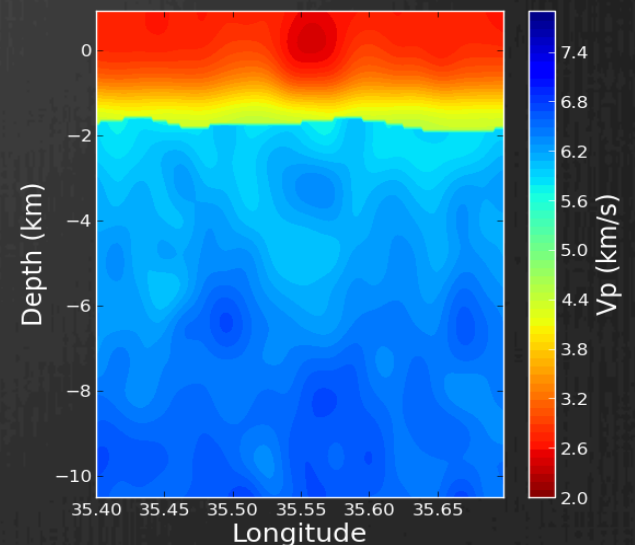
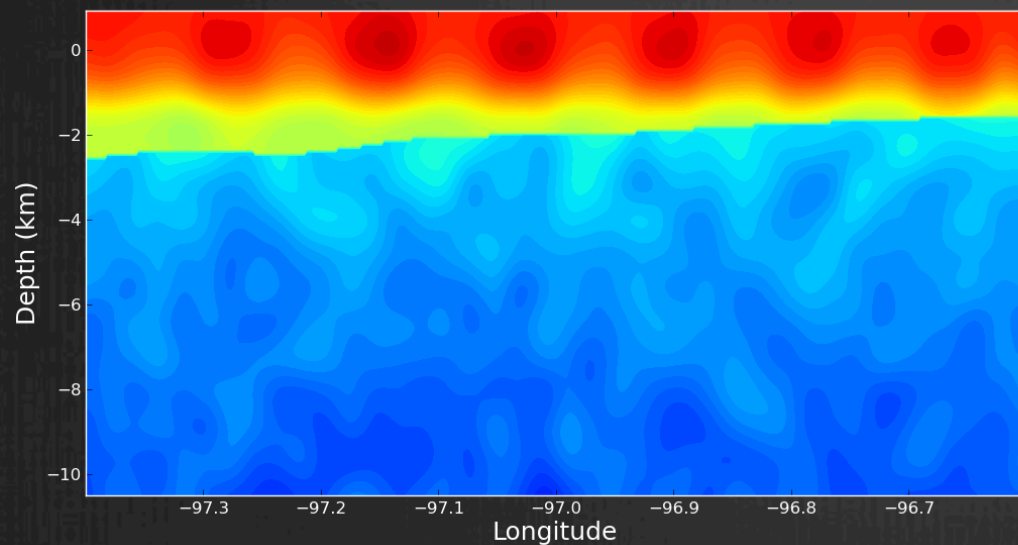
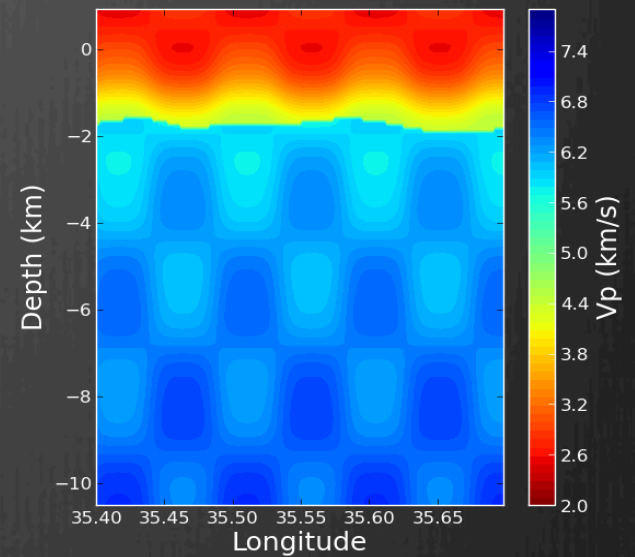
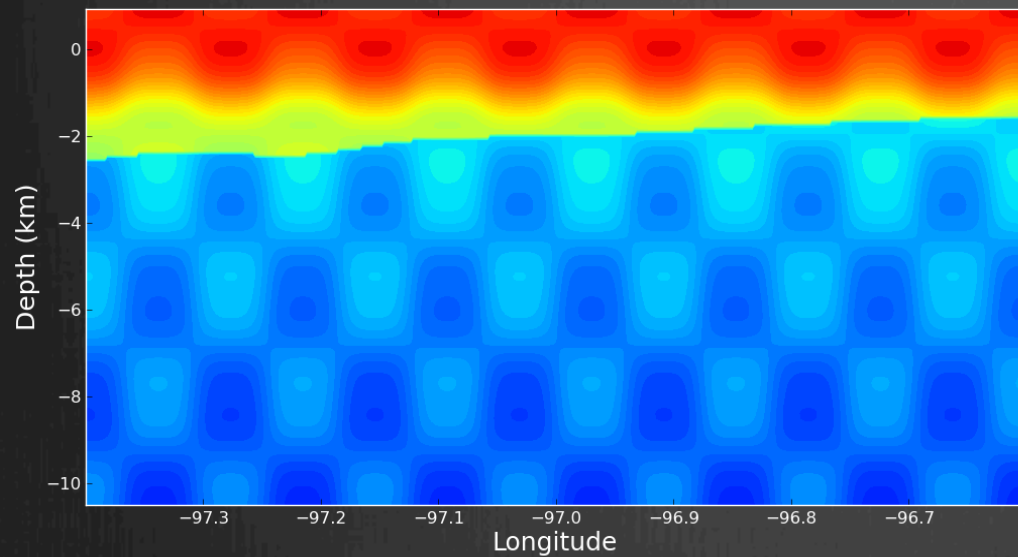
# Checkerboard Test – 1km deep



# Checkerboard Test – 3km deep



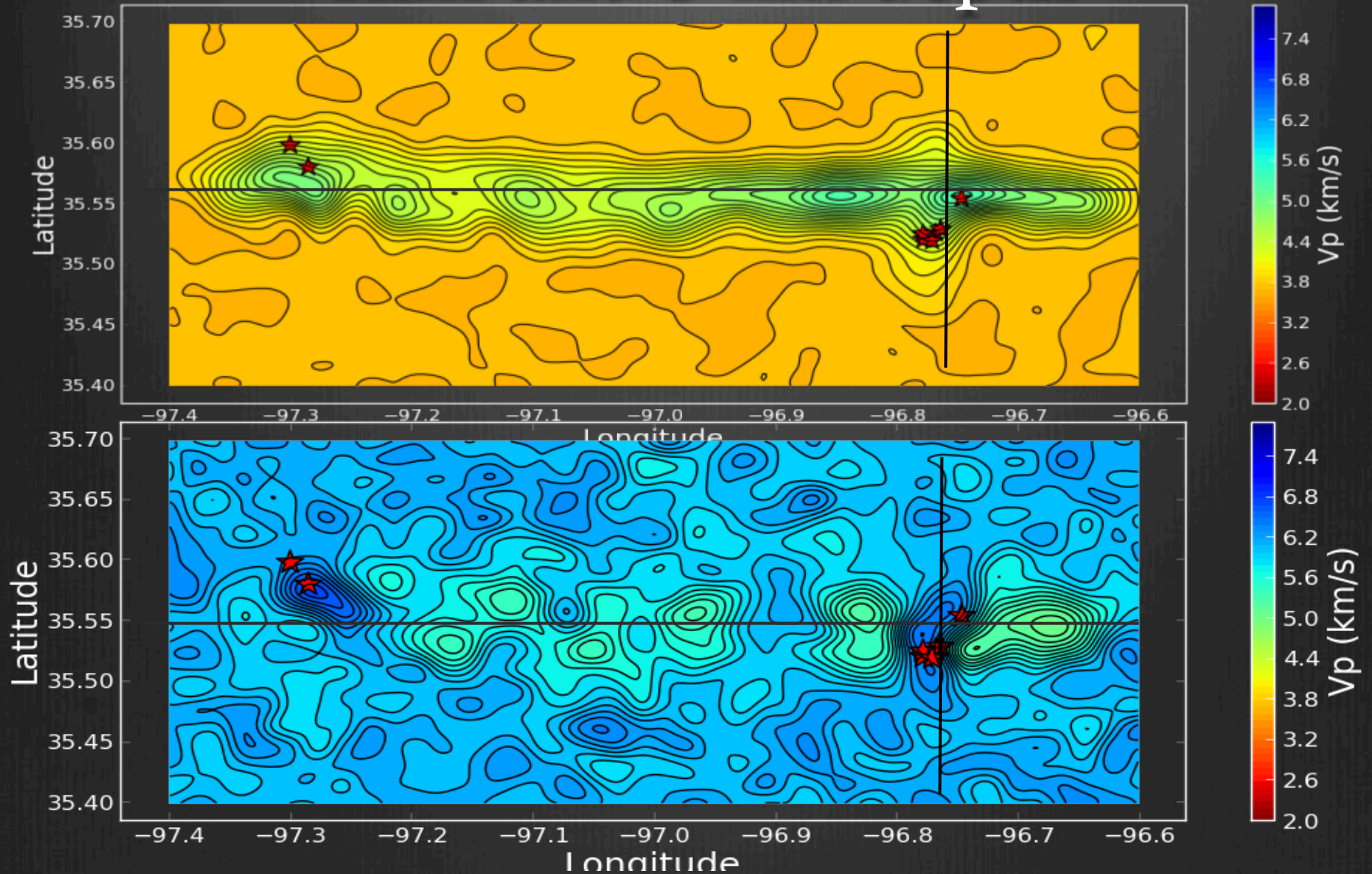
# Checkerboard Test



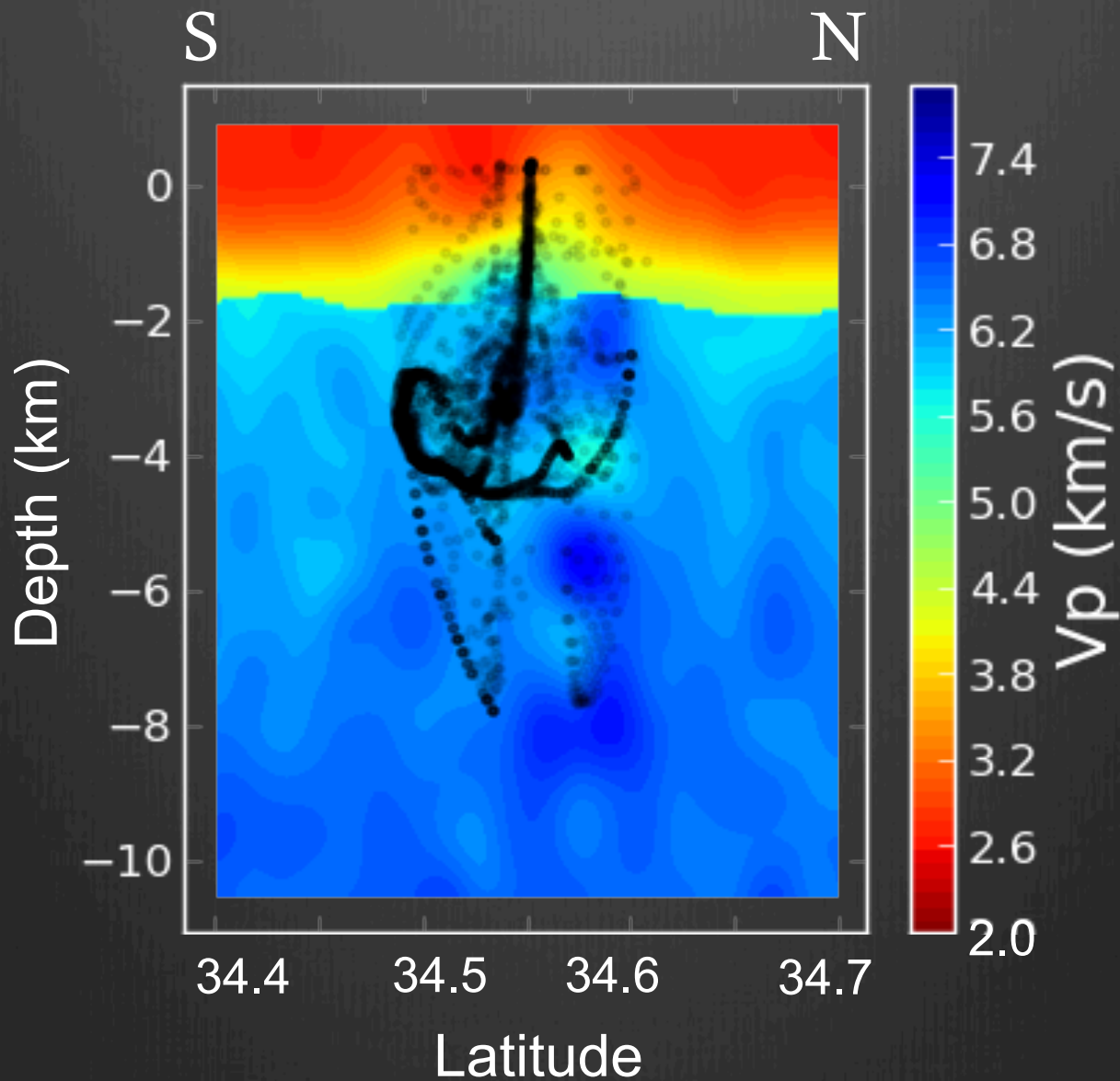


# Tomographic Inversion

## 1km and 3 km depth

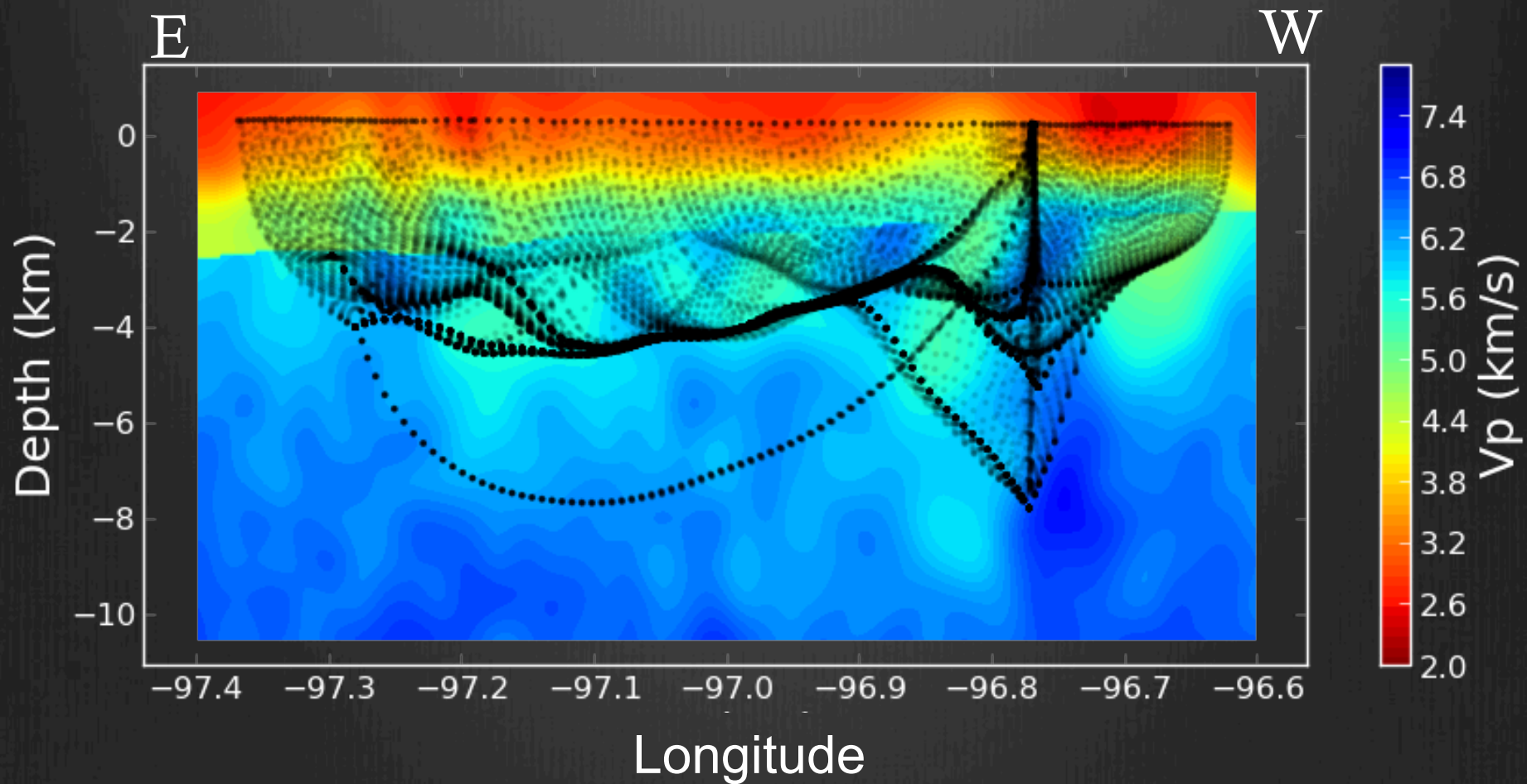


# Tomographic Inversion



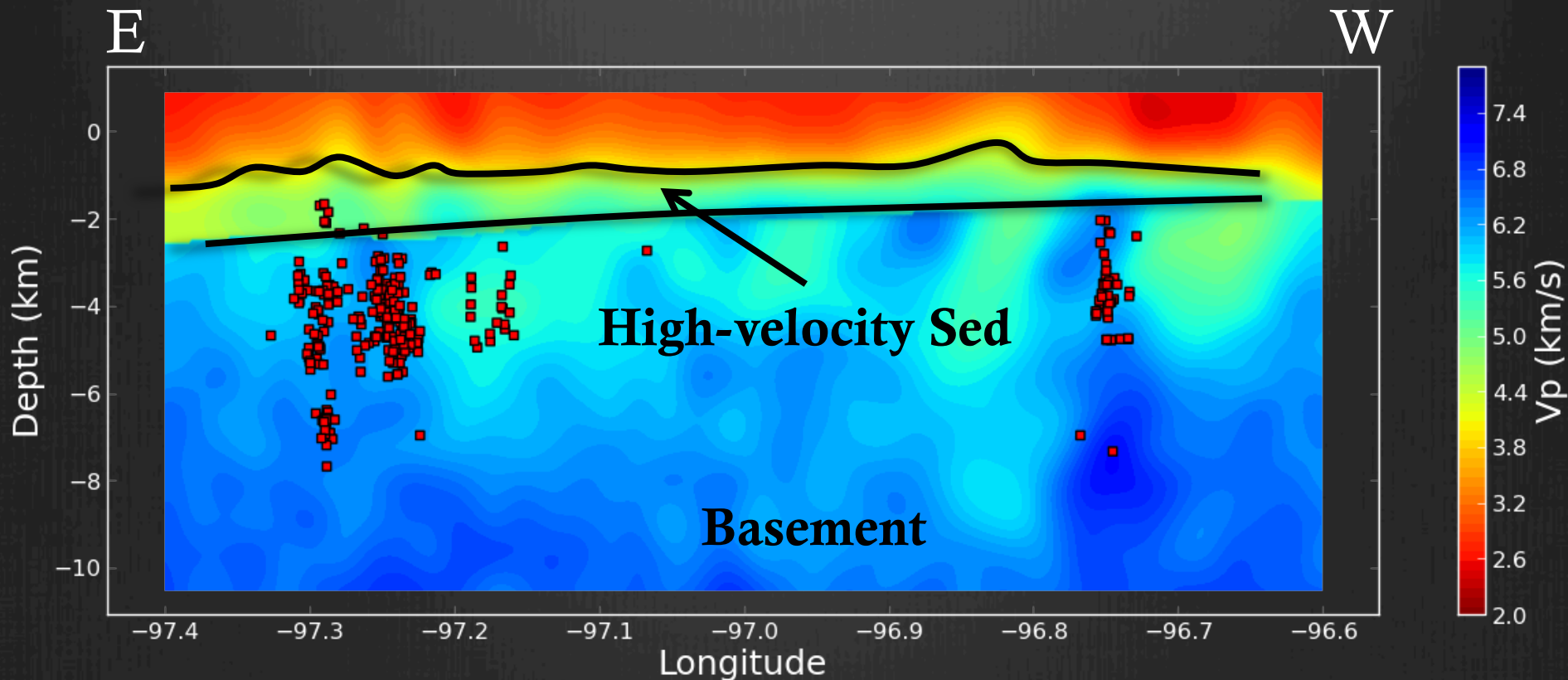


# Tomographic Inversion



# Conclusions

- ⊗ High velocity sedimentary layer does not follow basement
- ⊗ Hypocenter locations are moderately correlated to velocity contrasts



# Further Work

- ⊗ Use inverted hypocenters to adjust travel times and iterate
- ⊗ In the center of the survey area, Luza and Lawson (1983) report a  $\sim 250\text{mT}$  negative magnetic anomaly with no corresponding gravity anomaly.
- ⊗ Integrate a gravity survey with state aeromag survey to correlate to velocity structure
- ⊗ Use filtering and trace stacking to enhance deeper reflections
- ⊗ Shrink checkerboard tiles. Rapid recovery of velocity and interface structure indicate current checkerboard tests probably understate survey resolution